Weatherproof Tubular Slip Ring Assembly

Model B8-4.3W

- 8 circuit weatherproof slip ring
- Compact design
- Mounts on shafts up to 4.3” [109.2 mm] in diameter
- Permanently lubricated bearings
- Rugged stainless steel construction
- Instrumentation quality rings and brushes

Description

Michigan Scientific’s *B8-4.3W Weatherproof Slip Ring Assembly* is ideal for applications which require the slip ring to be sealed and mounted directly on a rotating shaft. Typically used for agricultural and heavy equipment PTO and drive shaft measurement applications, this model employs specially designed seals that provide weatherproof protection from water, mud, snow, dust, and other contaminants (unit is not submersible). It is designed to fit on shafts up to 4.3” in diameter and make electrical connection to strain gages, thermocouples, or other sensors that have been installed on rotating equipment. The slip ring brushes and rings are made of precious metals which minimize noise and enable the assemblies to be used for low level instrumentation signals.

The eight circuit capacity of this slip ring allows for more than one full bridge strain gage measurement channel. This is particularly useful for drive shaft applications where both torque and axial measurements are needed. When strain levels are very small, e.g. most axial strain measurements, it is beneficial to use Michigan Scientific’s *Rotating Strain Gage Amplifiers*. If accurate temperature measurements are required use of Michigan Scientific’s *Thermocouple Amplifier* is recommended. Locating precision amplifiers on the rotating side of the slip ring improves signal quality because the amplifier is located closer to the sensor. This reduces errors due to long lead wires, connector resistance variations, electro-magnetic interference, and temperature gradients across slip ring contacts.

Connections are made through color coded solder terminals located on the slip ring rotor and a connector on the slip ring stator. The compact design of these slip rings make them ideal for applications where limited space is available.

Specifications

Circuits	8
Current Capacity per Circuit	1A
Temperature Range	-40°F to 250°F (-40°C to 121°C)
RPM Rating	3500 RPM
Maximum Peak Noise*	0.1Ω
Width	2.1 in (53.3 mm)
Weight	12.8 lbs (5.8 kg)
Output Connector	PT02E-12-10P
Mating Connector	PT06E-12-10S
* Resistance variation across slip ring contact.	

8500 Ance Road
Charlevoix, MI 49720
Tel: 231-547-5511
Fax: 231-547-7070

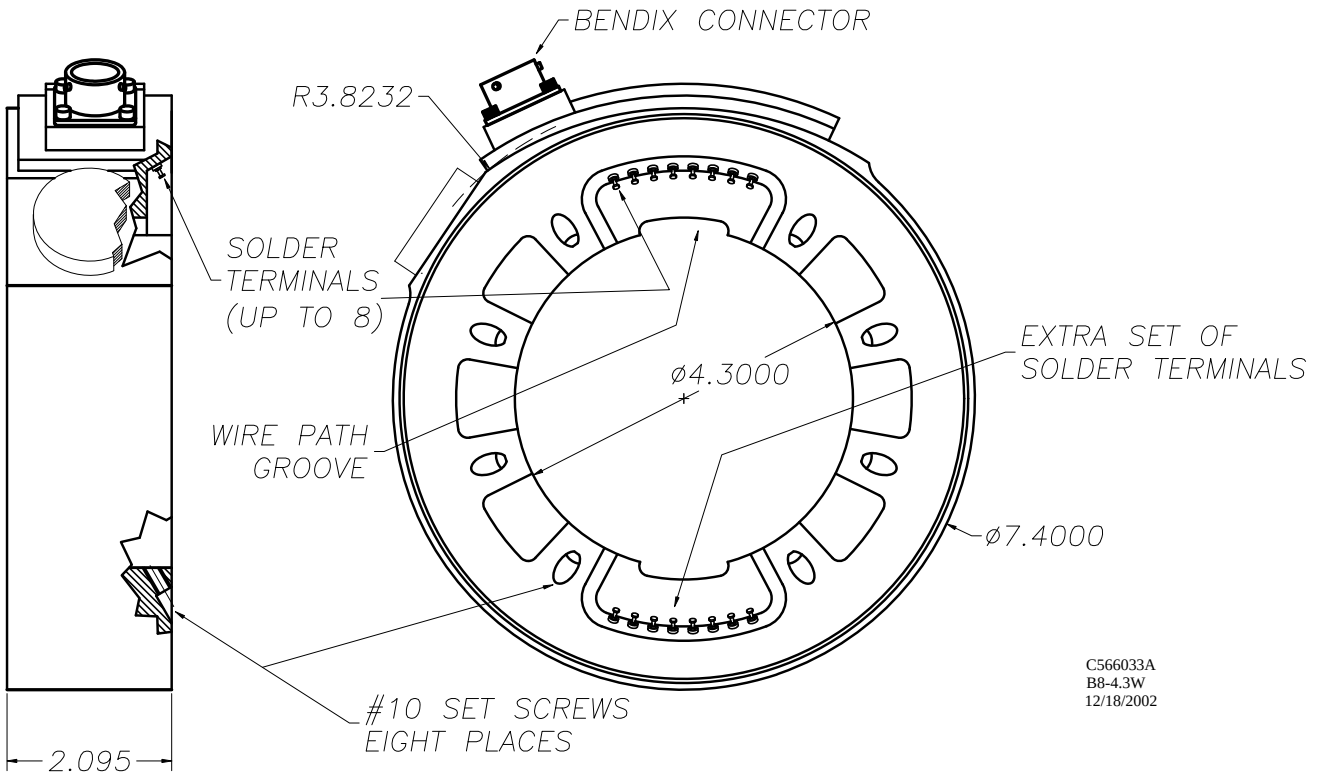
MICHIGAN SCIENTIFIC corporation
http://www.michsci.com
Email: mscinfo@michsci.com

321 East Huron Street
Milford, MI 48381
Tel: 248-685-3939
Fax: 248-685-5406

Rev: 6/18/12

Weatherproof Tubular Slip Ring Assembly

B8-4.3W Configuration



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Slip Ring & Rotation Sensor Assembly

SR/ERT Series

- 10, 20, or 36 slip ring connections
- Encoder or resolver rotation sensor
- Additional encoder electronics (built in)
- Available with or without weatherproof seals
- Different rotor styles
- Circular connectors or color coded solder terminals
- Instrumentation quality rings & brushs
- Sealed, corrosion resistant metal housing
- Lightweight and compact
- Quick deliver

Description

The SR/ERT Series is used when slip rings and/or a rotation sensor need to be mounted at the end of a rotating shaft. The gold alloy slip rings are used to make high quality electrical connection to strain gages, thermocouples, or other sensors that have been installed on rotating machinery. Current capacity is 0.5A per connection and the maximum peak resistance variation is 0.1W. The rotation sensor is used to measure rotational velocity, angular position, and direction of rotation. The rotation sensors do not use any of the slip ring connections.

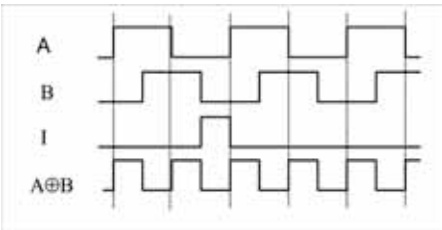
The **housings** are 3 to 5 inches long, depending on the number of slip rings. They weigh about 15 ounces. The rotors are made from high strength stainless steel. The stators are lightweight, nickel-plated, aluminum. Threaded holes are provided for attaching a rotation restraint. Connection information is permanently engraved on the housing. Circular connectors or solder terminals are offered as wiring terminations. A circular connector is usually specified on the stator. On the rotor, test applications needing a quick disconnect specify circular connectors. If small size is needed, solder terminals are specified on the rotor. In both cases there is also a choice of orientation. For outline drawings, contact Michigan Scientific or visit our web site at www.michsci.com.

All the housings in this series have been designed to accept contacting **rotary seals**. Units ordered with these seals (choice W) are completely weatherproof and can survive days of total submersion. The seals limit operation to 2000 rpm maximum. Most wet weather applications, like automotive wheels, are within this range. For higher speeds in dry conditions, order units without the contacting rotary seals. Units without seals are capable of the following speeds: 10 rings: 10,000 rpm, 20 rings: 4000 rpm, and 36 rings: 2400 rpm. Unit torque with seals is 21 inch-ounces. Unit torque without seals is 3 inch-ounces. If the application requires a high speed, weatherproof slip ring & encoder, consider units with noncontacting labyrinth seals in the SR/E512 series.

Rotation sensor choices E256, E360, E500, & E512: Four optical **encoder** resolutions are offered, see the table below. Each of these encoder choices has 4 outputs, shown graphically below. Outputs A and B are in quadrature (exactly 90° out of phase). Output I is an index pulse. Output A⊕B is the exclusive OR of A and B, which doubles the basic resolution of the encoder. The outputs, 0 to 5 volt pulses, can drive TTL loads. The encoders will operate from a +5 to +20 Vdc, 100 mA power supply. Temperature range is -40F to +212F. The encoders have metal code wheels and rugged electronics so they tolerate shock and vibration. They are also protected from incorrect wiring up to 20 volts. Accuracy of encoder systems is 0.25° (maximum cumulative error).

Encoder choices	Outputs:Pulses per revolution A	B	I	A⊕B
E256	256	256	1	512
E360	360	360	1	720
E500	500	500	1	1000
E512	512	512	1	1024

ENCODER OUTPUTS



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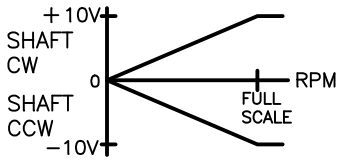
Slip Ring & Rotation Sensor Assembly

SR/ERT Series

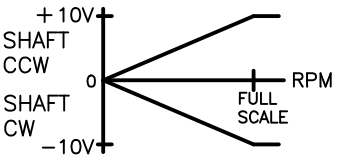
Rotation sensor choices T256, T360, T500 & T512: Additional **encoder electronics** can be built into the encoder units. The electronics adds two analog outputs, a voltage proportional to shaft velocity (similar to a tachometer) and a voltage proportional to the angular position of the shaft. The analog outputs are easier to record than the digital encoder outputs, which require high sampling rates. Both analog outputs are updated at each pulse of encoder output A, so they are instantaneous, not average values. The encoder electronics will operate from a +6 to 16 Vdc, 400 mA power supply. Temperature range is -40F to +185F.

Full scale for the **angular position output** is +10V for rotation in either direction.

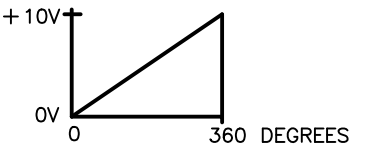
Full scale for the **velocity output** is +10V for rotation in one direction and -10V for rotation in the opposite direction. Two velocity sensitivities and direction of rotation are usually programmed into each unit. Two pins in the stator connector are designated as option pins, through which the user selects 1 of 4 combinations. For example, units used on our torque wheels are normally programmed to output 10V at 1000 rpm with option pin #1 open. With option pin #1 grounded, full scale is 1800 rpm. Option pin #2 sets the polarity, or direction of rotation, viewing the end of the shaft. With pin #2 open, CW rotation results in a positive velocity output. When pin #2 is grounded, CCW rotation results in a positive velocity output.



VELOCITY OUTPUT WITH OPTION PIN #2 OPEN



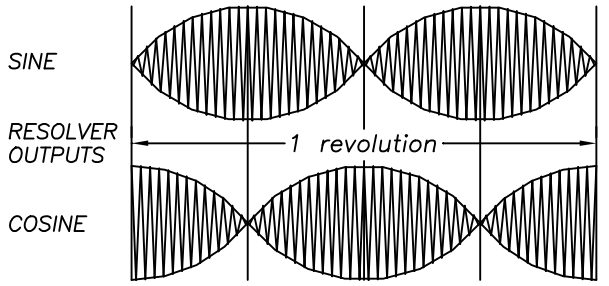
VELOCITY OUTPUT WITH OPTION PIN #2 GROUNDED

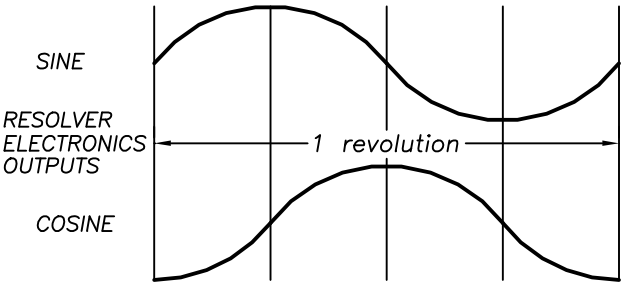


POSITION OUTPUT (0 IS AT INDEX PULSE)

Because the velocity output is like a dc tachometer, we sometimes refer to it as the tachometer circuit. However, unlike a tachometer, there is no commutation ripple, it works down to 0 rpm, linearity and accuracy are better, it is small and lightweight, and the performance does not degrade with use.

Rotation sensor choice R360: A **resolver** can be specified instead of an encoder. The resolver is an analog rotation sensor with two outputs labeled sine and cosine. The outputs can be passed through the same type of filters as strain gage or other analog sensor signals coming through the slip rings. Then the rotation signal will remain in phase with the sensor signals. The resolver requires additional external electronics for excitation and for processing the outputs. (Michigan Scientific makes resolver electronics, see model RESSC-2-12V in the electronics section of the catalog.) A resolver is an absolute position sensor. Its' angular position is known as soon as the excitation and electronics is turned on, an index pulse does not have to be located before the shaft position can be determined. Temperature range is -40F to +250F. Accuracy of the resolver is 0.25°. System accuracy, which includes the electronics, is within 1°. The resolver option is most often used with 6 axis wheel load transducers.





Ordering information

Part numbers and pricing can be found in the "Price List and Accessories" section of the catalog. Part numbers are also on the outline drawings, which are on our web site at www.michsci.com

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Fiber-Optic Systems - 1 MHz ANALOG LINK

Model FO-HBST/HBSR

- Monitor / Stimulate equipment under test (EUT) at Bandwidths from DC to 1 MHz
- RFI/EMI validated for EMC at 200V/m (46dBVm) from 500 kHz to 18 GHz and 600V/m (pulsed 5% duty-cycle & 5µs rise-time) 1GHz to 2.5 GHz
- Low-Power circuitry for operating >16 hours with 3 alkaline 'AA' batteries
- TX slide-switch provides full-scale input ranges of ±8, ±16, and ±48 VDC
- RX jumpers provides full-scale output ranges of ±4, ±8, and ±16 VDC

Description

The *FO-HBST* and *FO-HBSR* form a versatile Fiber-Optic Analog Signal TX/RX pair. Input signals at pre-selected full-scale input levels and at bandwidths from DC to 1 MHz may be transmitted fiber-optically in either direction by transposing the module .

The tester can externally access a 3-position slide switch to select the transmitter module full-scale input level of ±8, ±16, or ±48 VDC. Internal gain jumpers in the receiver module are factory configured for full-scale output levels of ±4, ±8 or ±16 VDC with ±16 VDC standard. Systems may be configured to other user defined full-scale inputs and outputs on request.

The satellite modules have shielding and special input/output filtering that provides high immunity from electromagnetic interference (EMI), electromagnetic pulse (EMP) or high voltages associated with plasma research. This allows for rigorous electromagnetic compatibility (EMC) testing/engineering. The satellite modules are validated for EMC up to 200 V/m (46 dB V/m) at 500 kHz to 18 GHz and 600 V/m (pulsed 5% duty-cycle &5µs rise-time) 1GHz to 2.5 GHz.

Three 'AA' batteries provide power for up to 25-hours. The supplied AC adapter is used for external power in place of batteries.

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SPECIFICATIONS

PARAMETER	SPECIFICATION
SYSTEM CHARACTERISTICS AND PERFORMANCE	
GENERAL	
TX/RX Signal Type	differential input / single-ended output
TX Full-Scale Ranges	slide-switch selectable for ±8, ±16, ±48 VDC
RX Full-Scale Ranges	jumper configurable for ±4, ±8, ±16 VDC
Bandwidth (±4 / ±8 V Range ONLY)	1 MHz (-3 dB) *typical*
Flatness (±4 / ±8 V Range ONLY)	±1 dB to 500 kHz *typical*
Rise/Fall Times	~ 300 ns (20-80%) *typical*
End to End Delay	<1.8 µs *typical*
Output Noise	<10 mV rms
Resolution (±8, ±16, ±48 V Full-Scale)	>4 mV/ 8 mV/ 24 mV
DC Gain Adjustment (Receiver)	-10% to +25% of scale
DC Offset Adjustment (Receiver)	±1 VDC
DC Offset Drift	<0.5% drift through temp. range
Over-Range Protection	±100 V continuous and ±350 V transient protection
Transmitter Input Impedance	
@ ±8, ±16, ±48 V	> 72.5k / 145k / 435kΩ
Receiver Output Impedance	100 Ω
Maximum Recommended External Load	1 KΩ (16mA)
Power Source	3-AA alkaline batteries or external adapter
Battery Life	
Transmitter	>25 Hours
Receiver (load and frequency dependent)	>16 Hours (use high-impedance load for max run time)
PHYSICAL	
Dimensions (L x W x H)	6.8 x 3.0 x 1.0 in (172 x 76 x 25 mm)
Weight [w/o Batteries]	13 oz (368.5 g) [10 oz (283.5 g)]
Input / Output Connector	BNC
Optical Connectors	ST
Optical Cables	multimode graded-index 62.5/125 µm or 100/140 µm
Optical Cable Length	1640 ft (500 m) max.
ENVIRONMENTAL	
Operating Temperature	-10º F to +185º F (-12º to +85º C)
Operating Humidity	95% R.H. max. non-condensing
EMC	300 V/m at 500 kHz to 1 GHz, 200 V/m at 1 GHz to 18 GHz and 600 V/m (pulsed 5% duty-cycle & 5µs rise-time) 1 GHz to 2.5GHz
QUALITY AND SAFETY	
CE Mark	Declaration of Conformity provided
RoHS & WEEE	Compliant

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